

The Control System of the New Small Whee Electronics for the ATLAS experiment

ENPERIN

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Contents

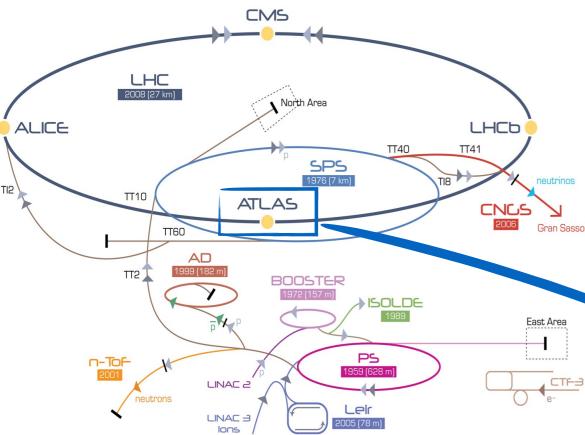
- Large Hadron Collider & ATLAS experiment
- New Small Wheel
- Electronics Overview & Architecture
 - FELIX & GBT-SCA
 - SCA OPC UA Server & Back-end APIs
- ATLAS Detector Control System
- NSW Detector Control System
- Electronics Control System
- DCS & DAQ interaction



3

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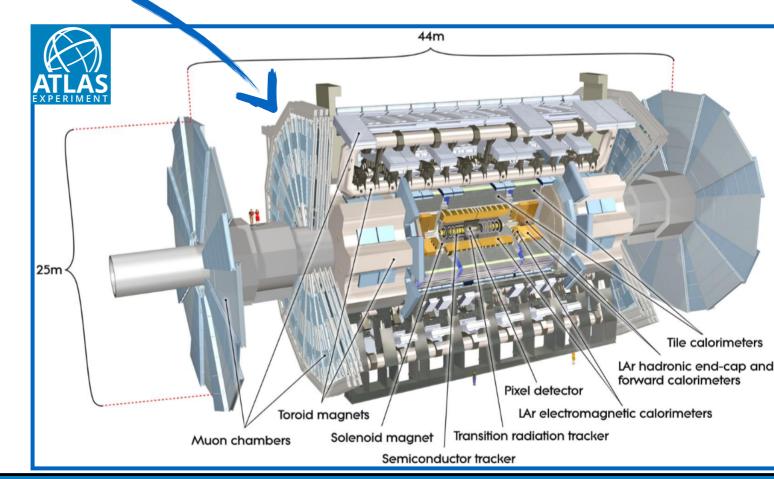
Large Hadron Collider The European Organisation for Nuclear Research:



- Largest of four LHC experiments
- 7000 tonnes, ~100 million read-out channels,
 3000 km of cables
- Contains 11 sub-detectors of different
 technologies in layer structure
- Built and operated by collaboration of >3000
 physicists
- Operation with collisions since end 2009

IMS

- French-Swiss borders @ 60-100m underground!
- 27 km circumference
- Provide beams of p-p, p-Pb, or Pb-Pb ions
- Plenty of experiments



The Control System of the New Small Wheel Electronics for the ATLAS experiment



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4

New Small Wheel

- <figure>
- The New Small Wheel (NSW) upgrade will replace the current Small Wheel of the ATLAS muon spectrometer to handle larger particle rates
 - Important for Run 3, vital for High Luminosity LHC (2028)





stdc MM chamber stdc the stdc

New Small Wheel The NS track re to ATLA issues • 16 se • 16 la

The NSW will provide high precision muon track reconstruction and trigger information to ATLAS, at high rates, thus eliminating the issues of the present SW.

- 16 sectors for each NSW
- 16 layers for each sector

- The NSW detectors:
- Micromegas (MM), mainly for precision tracking, also for trigger
- small Thin Gap Chambers (sTGC), mainly for trigger, also for precision tracking

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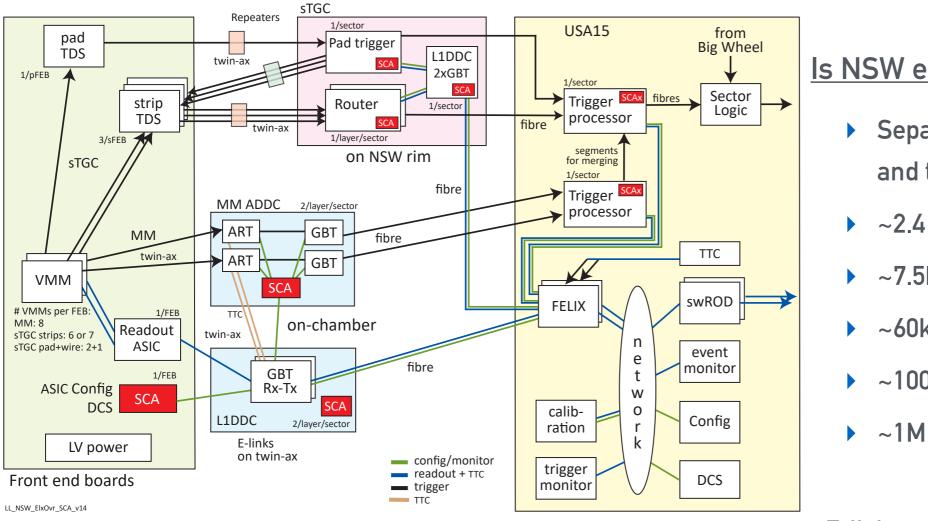
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5

NSW Electronics Overview

ATLAS

The New Small Wheel is a fully redundant trigger and tracking detector system, adequately supported by an advanced electronics scheme and ready to handle the challenges of increased instantaneous luminosity at the High Luminosity LHC.



- 54k on detector readout ASICs read out by E-links to GBTx ASICs
- 1024 on-detector trigger encoders configured by 512 GBT-SCAs
- 256 Router FPGAs and 32 Pad Trigger FPGAs on the rim of the NSW
- All of the above configured and monitored by ~6400 GBT-SCA ASICs
- 64 FPGAs for Trigger Processor in USA15

<u>Is NSW electronics system really "Small"?</u>

- Separate configuration/monitor, readout and trigger path
- ~2.4 millions readout channels
- ~7.5k electronics boards
- ~60k ASICs
- ~100k parameters for monitor
- ~1M registers for Configuration

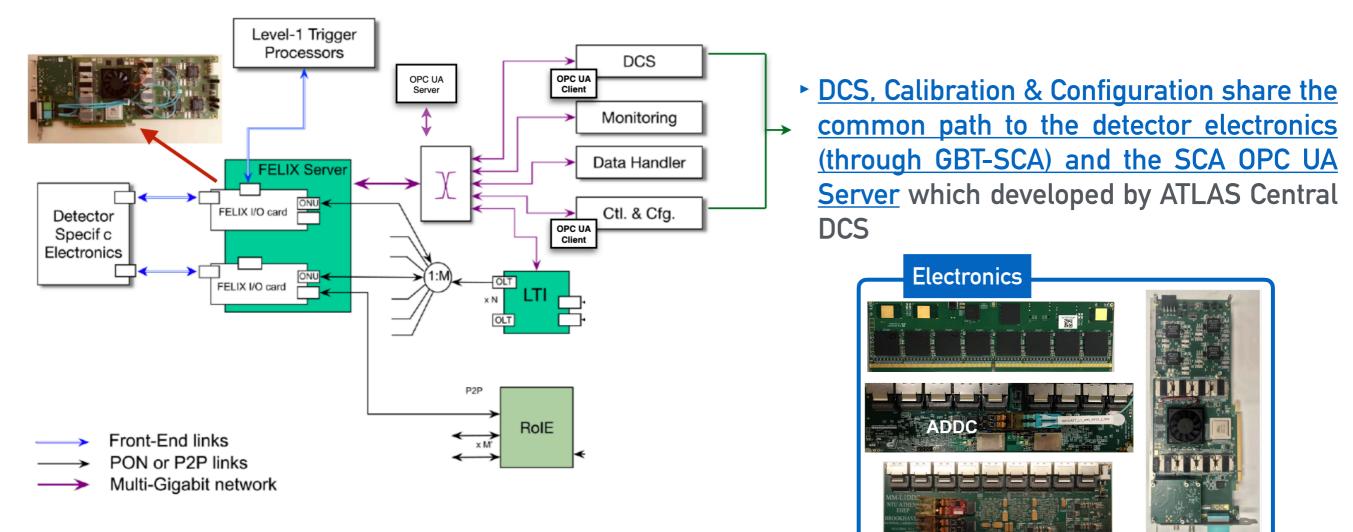
E-links used for:

- L1 Accept data + Data monitoring
- BC clock and TTC signals
- Configuration of ASICs
- Monitoring temperatures and voltages
- FPGA configuration

The Control System of the New Small Wheel Electronics for the ATLAS experiment

NSW Electronics Architecture

- The NSW Electronics architecture lies on the newly introduced readout scheme of ATLAS
- It has mainly three new hardware components:
 - FELIX Optical link aggregator system / TTC distributor / Busy. This is a server PC which host two BNL712 PCIe boards (24 optical links / each on NSW)
 - Data handler server or swROD system Software based readout driver
 - ALTI TTC system Replacement module of the legacy TTC system (vi/vx LTP)





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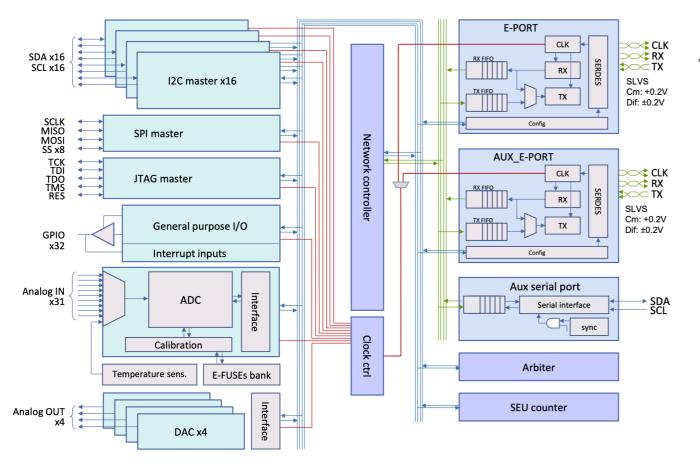
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GBT-SCA

ATLAS

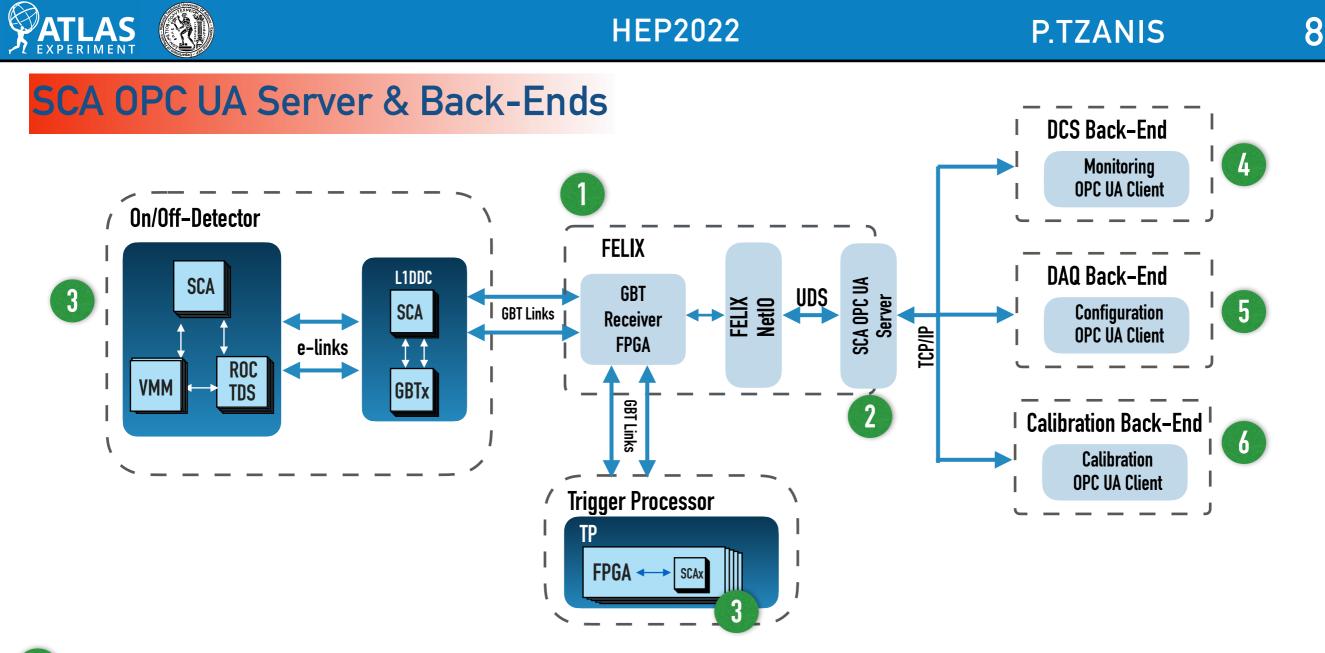


The GBT-SCA ASIC (Giga-Bit Transceiver - Slow Control Adapter) is the part of the GBT chipset which purpose is to distribute control and monitoring signals to the front-end electronics embedded in the detectors.



The user interface ports are:

- 1 SPI serial bus master Interface
- 16 independent I²C master serial bus channels
- 1 JTAG master Interface
- ► 4 DAC (8-bit)
- 32 General Purpose digital IO lines (GPIO)
- 31 ADC (12-bit)



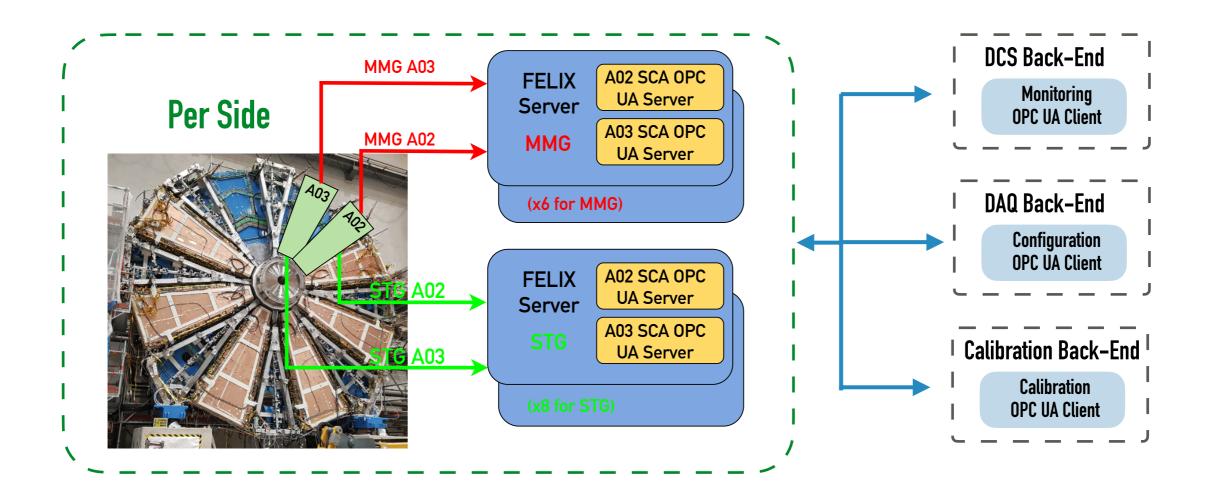
- Prepare FELIX by configuring the e-links ports
- 2 Initialise SCA OPC UA server by indicating the e-links to connect to
- 3 Establish communication between SCAs and SCA OPC UA Server via the FELIX
- 4 Monitor the various temperature and voltage levels of the electronics via SCA OPC UA Server and DCS
- 5 Configuration of the various electronics via the SCA OPC UA Server and the NSWConfiguration
- Calibration of the various electronics via the SCA OPC UA Server and the NSWCalibration

The Control System of the New Small Wheel Electronics for the ATLAS experiment

System setup

The system setups consists of:

- 28 FELIX servers (12 for MMG, 16 for STG)
- 32 SCA OPC UA Servers
- I SCA OPC UA Server per sector

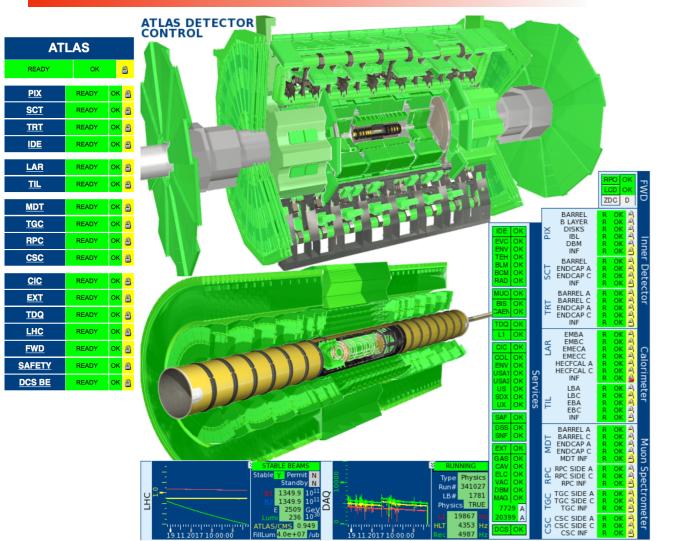




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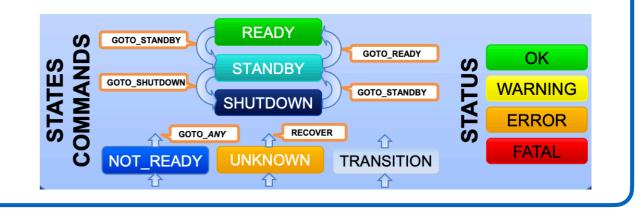
ATLAS Detector Control System





State Machine Hierarchy

- Detector control mapped to state machine hierarchy above SCADA layer
- Using JCOP FSM software framework
- Device States are propagated upwards using state rules, Commands propagated downwards
- Error handling upwards using parallel tree of Status objects linked to device alarm



Operator Control

- Alarm Screen enabling quick recognition and response to problems
- Homogeneous navigation through state machine hierarchy for operator with custom HMI
- Each state machine object has associated panel (synoptics, trends etc.)
- Access control mechanism
- Web monitoring, no load on Back-End, history mode

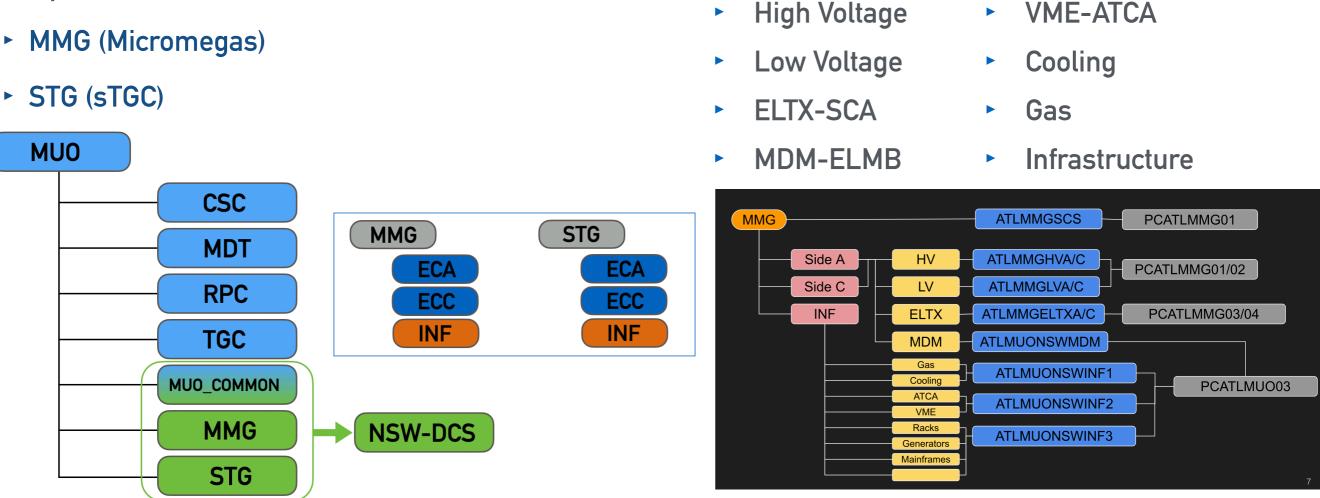
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NSW Detector Control System

Due to its complexity and long-term operation, the NSW requires the development of a sophisticated DCS. The use of such a system is necessary to allow the detector to function consistently and safely as well as to function as a seamless interface to all sub-detectors and the technical infrastructure of the experiment.

The plan is to have 2 new sub-detectors:

<u>Main projects:</u>



NSW DCS architecture and it's integration with the Muon DCS have been finalised. The top node of both MMG and STG will propagate its state and receive commands from the ATLAS overall DCS.

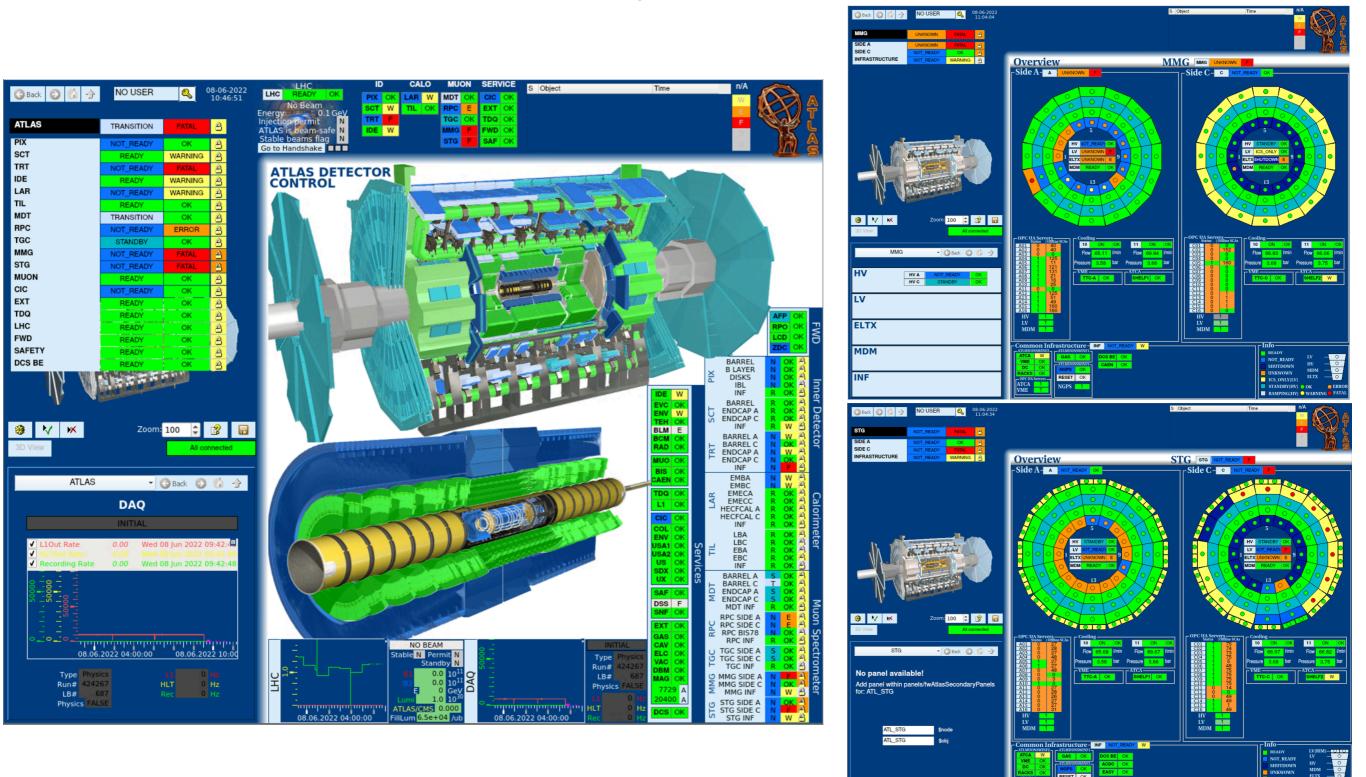
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ATLAS DCS Integration

ATLAS

Since 1 week, MMG&STG DCS have been integrated into the ATLAS & Muon DCS !!!



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Electronics control system

For the NSW electronics safe operation, an advanced control system within the ATLAS DCS is required for the electronics monitoring using the SCA chip, which is installed on the 7000 front-end boards of the NSW.



Features:

- ► ~7000 GBT-SCA
- Run over the common SCA OPC UA Server
- ~100k parameters
 - Power & temperature sensors
 - On-chip temperatures and information
 - Diagnostics information
 - Alarm handling on each parameter
- Following Muon's existing look and command architecture
- Hierarchy of Finite State Machine (FSM)
- Facilitate the shifter/expert operations

For each individual layer, a main panel has been developed, providing the user with useful information, reflecting the state and status of the detector.

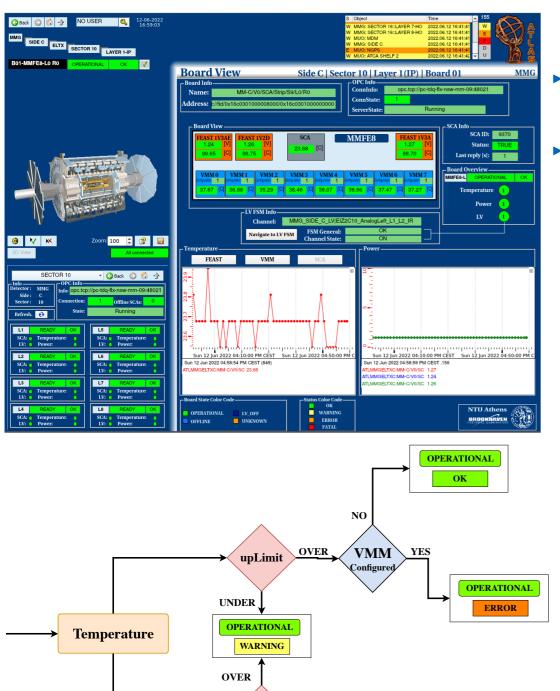


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DAQ-DCS Interaction

ATLAS



downLimit UNDER

OPERATIONAL

- On FEBs equipped with VMM, SCA Analog Input common for VMM calibration and temperature monitoring
- Thus, during calibration VMM shows fake temperature values so a DDC plug between DCS-DAQ should be implemented
 - Solution found via the common SCA OPC UA Server!

DCS and DAQ are on the same SCA OPC UA path

- Central DCS developed the FreeVariable concept, which is a OPC UA item which can be controlled and monitored in both DCS and DAQ clients.
- So, during Calibration run, the DCS will monitor the configuration status for this specific VMM of the FEB and the alarm will be disabled corresponding FEB's VMM
 - More DAQ-DCS interaction:
 - FELIX monitoring
 - GBT e-link health status



Summary

- The NSW is a fully redundant trigger and tracking detector system supported by an advanced electronics scheme and ready to handle the challenges of increased instantaneous luminosity at the HL LHC
- Due to its complexity and long-term operation, the NSW requires the development of a sophisticated DCS
- The NSW Electronics system is really challenging due to the massive number of boards (ASICs, FPGAs)
- Another challenge is the dependance of the NSW DAQ on new technologies based on FELIX and GBT-SCA
- Use of common SCA OPC UA Server path in order to simplify the NSW DCS/DAQ procedure
- System setup, architecture, operation and technical reviews have been finalised
- The NSW Electronics control system has been implementation into ATLAS & Muon DCS!
- Continuous optimisation is on-going





Thanks for your attention!

- Questions ?
- Comments ?





The Control System of the New Small Wheel Electronics for the ATLAS experiment



ELTX DCS

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The Control System of the New Small Wheel Electronics for the ATLAS experiment



ELTX DCS

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The Control System of the New Small Wheel Electronics for the ATLAS experiment



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| Detector : MMG Side : C | opc.tcp://pc-tdq- | flx-nsw-mm | -09:48021 | Type: ADDC LV: O SCA: O Temperature: O | | Type: MMFE8 LV: SCA: Temperature: |
| | nnection: 1 | Offline SC/ | As: 0 | 11 PERATIONA OK Power: | 3 | 12 PERATIONA OK Power: |
| | State: | Running | | Type: MMFE8 LV: O SCA: O | | Type: ADDC LV: O SCA: O |
| Refresh. 🔂 | | riuming | | 09 PERATIONA OK Power: | | 10 PERATIONA OK Power: |
| | | 0.5.1.5 | | | | Type: MMFE8 LV: • SCA: • |
| L1 READY | OK L5 | READY | OK | | | 08 PERATIONA OK Power: |
| SCA: Temperature | · · · · · · · · · | Tempera Power: | | | 2 | Power: |
| | | | | Type: MMFE8 LV: O SCA: O O5 PERATIONA OK Power: | | |
| L2 READY | OK L6 | READY | OK | 05 PERATIONA OK Power: | | |
| SCA: Temperature | | Tempera | ture: O | | | Type: MMFE8 LV: SCA: |
| LV: O Power: | | Power: | | | 0 | 04 PERATIONA OK Power: |
| L3 READY | OK L7 | READY | OK | Type: MMFE8 LV: O SCA: O | | |
| SCA: O Temperature | | Tempera | ture: 😑 | 01 PERATIONA OK Power: | | |
| LV: O Power: | | Power: | 0 | Layer State Color Code – Board State Color Code | | |
| L4 READY | OK L8 | READY | ОК | READY | DISABLED | NTU Athens |
| SCA: O Temperature | | Tempera | | NOT_READY OPERATIONAL | LV_OFF EPROP | |
| LV: O Power: | | Power: | Ŏ | SHUTDOWN OFFLINE | UNKNOWN FATAL | NATIONAL LABORATORY |
| 1 | | | | | TATAL | |

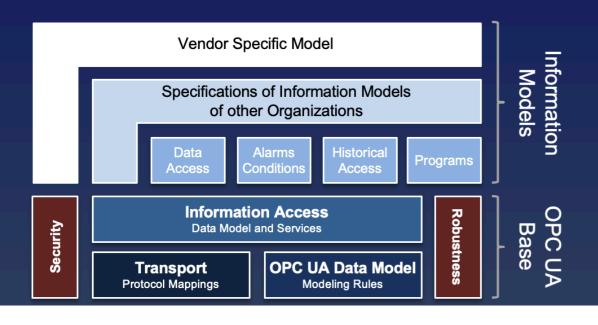
The Control System of the New Small Wheel Electronics for the ATLAS experiment

OPC Unified Architecture

OPC Unified Architecture

Industrial machine-to-machine communication protocol for interoperability

- Originally developed by OPC Foundation for IoT applications (keyword Industry 4.0)
- OO Information modeling capabilities
- Enhanced security, performance and scalability
- Supports buffering, session mgmt, pub-sub, per-connection heartbeats/timeouts, discovery
- Multi-platform implementation, lightweight I embedding possible
- Commercial SDKs available with stack from OPC foundation or open source stack implementations (C, C++, Java, JS, Python) for servers and clients



- Excellent experience in ATLAS since 2012
- Fully supported by JCOP
- Still requires expertise and effort in programming with OPC UA ...
- Provide development environment and generate OPC UA related code?





21