Robinson–Trautman spacetimes in the Einstein–Gauss–Bonnet theory

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Plan of the talk

- Motivation and preliminaries
 - Our goal
 - General relativity
 - Modifying general relativity
 - Einstein-Gauss-Bonnet theory
 - Robinson-Trautman spacetimes
- Our results
 - rr-component
 - rp-component
 - ru-component, etc.
 - Constraints on the Weyl tensor
- Summary

Our goal General relativity Modifying general relativity Einstein–Gauss–Bonnet theory Robinson–Trautman spacetime

Motivation: Why study RT spacetimes in EGB theory?

General relativity in D = 4: the best theory of gravity we have!

General relativity in D > 4: interesting toy model

RT in D = 4 **GR**: Weyl algebraic type II and more special (black holes, C-metric, gravitational waves, ...)

RT in D > 4 **GR**: Weyl algebraic type D (black holes only)

Is this D = 4 versus D > 4 discrepancy due to: the gravity theory or the geometric nature of RT class?

Study RT class in the natural D > 4 GR extension, i.e., **in EGB theory**!

Preliminaries: General Relativity

General Relativity formulated by a variational principle:

• the vacuum Einstein–Hilbert action in any dimension *D*

$$S = \int d^D x \sqrt{-g} \frac{1}{k} \Big(R - 2\Lambda \Big)$$

• $\delta S = 0$: the equations of motion

$$R_{\mu\nu} - \frac{1}{2}g_{\mu\nu}R + g_{\mu\nu}\Lambda = 0$$

Einstein's equations: system of 2nd order non-linear PDEs

Our goal General relativity Modifying general relativity Einstein-Gauss-Bonnet theory Robinson-Trautman spacetimes

Preliminaries: Extensions of GR

Why to modify Einstein's general relativity?

- cosmological issues: dark energy, dark matter
- small scales: singularities, compatibility with quantum description

How to modify Einstein's general relativity?

- number of dimensions
- various (exotic) matter contributions
- geometry

Preliminaries: EGB theory – action

- non-trivial representative of Lovelock gravities (Lovelock 1971)
- the heterotic string theory limit for low energies e.g. (Gross and Sloan 1987)

It is introduced via the **Gauss–Bonnet term** in the action:

$$S = \int d^{D}x \sqrt{-g} \left[\frac{1}{k} (R - 2\Lambda) + \gamma L_{GB} \right]$$

where the L_{GB} stands for

$$L_{GB} = R^{cdef} R_{cdef} - 4R^{cd} R_{cd} + R^2$$

where *R* is the Ricci scalar, and Λ , *k* and γ are constants ($\gamma = 0 \Leftrightarrow GR$).

EGB theory preserves the 2nd order field equations and is thus the natural extension of general relativity to higher dimensions.

Our goal General relativity Modifying general relativity Einstein-Gauss-Bonnet theory Robinson-Trautman spacetime:

Preliminaries: EGB theory – field equations

The field equations are obtained using $\delta S = 0$:

$$R_{ab} - \frac{1}{2}R\,g_{ab} + \Lambda\,g_{ab} + 2k\gamma\,H_{ab} = 0$$

where

$$H_{ab} \equiv R R_{ab} - 2R_{acbd} R^{cd} + R_{acde} R_b^{cde} - 2R_{ac} R_b^{c} - \frac{1}{4} g_{ab} L_{GB}$$

with

$$L_{GB} \equiv R_{cdef} R^{cdef} - 4 R_{cd} R^{cd} + R^2$$

Our goal is:

- to explicitly derive and analyse these 2nd order equations for the Robinson–Trautman geometric ansatz
- to compare properties of obtained solutions in the EGB gravity with those of D > 4 GR

Robinson-Trautman spacetimes

Preliminaries: Geometry of null congruences

The transverse behavior of a geodesic congruence generated by a null vector field *k* is characterized by **optical scalars**.



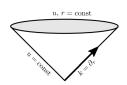
$$\Theta = \frac{1}{D-2}k_{;a}^a$$
 $\sigma^2 = k_{(a;b)}k_{;b}^{a;b} - \frac{1}{D-2}(k_{;a}^a)^2$ $A^2 = -k_{[a;b]}k_{;b}^{a;b}$

$$A^2 = -k_{[a;b]}k^{a;b}$$

Robinson-Trautman geometries: spacetimes admitting non-twisting, shear-free and expanding null geodesic congruence.

Preliminaries: RT geometries – adapted coordinates

Twist-free condition $k_{[a;b]} = 0 \Leftrightarrow \exists$ **null foliation** with k normal D-dim non-twisting spacetime in r, u, x^p (p = 2,..., D-1) coordinates:



- u = const labels null hypersurfaces
- $k = \partial_r$ is a generator of a non-twisting congruence
- *r* is an affine parameter along such a congruence
- $u = \operatorname{cst.} \wedge r = \operatorname{cst.} \text{ is } D 2\text{-dim space } g_{pq}$

The non-twisting metric g_{ab} becomes:

$$ds^{2} = g_{pq}(r, u, x) dx^{p} dx^{q} + 2g_{up}(r, u, x) dx^{p} du - 2du dr + g_{uu}(r, u, x) du^{2}$$

Shear-free condition:

$$g_{pq,r} = 2\Theta g_{pq} \quad \Leftrightarrow \quad g_{pq} = \exp\left(2\int \Theta(r,u,x)\,\mathrm{d}r\right)h_{pq}(u,x)$$

Results: rr-component

For *simplicity* and in *analogy with GR* we set:

$$g_{up}(r,u,x)=0$$

and the RT metric, we want to study, becomes:

$$ds^{2} = g_{uu}(r, u, x)du^{2} - 2dudr + \mathcal{R}(r, u, x)h_{pq}(u, x)dx^{p}dx^{q}$$

The EGB field equations *rr***-component** takes the form:

$$\begin{split} (\Theta_{,r} + \Theta^2) \big[D - 2 + 2\kappa \gamma (D - 4) \big({}^sR + (D - 2)(D - 3) \Theta^2 g_{uu} \\ - (D - 3) \Theta g^{mn} g_{mn,u} + 4(D - 3) g^{mn} \Theta_{,m} \Theta_{,n} \big) \big] = 0 \end{split}$$

Two branches of solutions w.r.t. $\Theta_{,r} + \Theta^2$

•
$$\Theta_r + \Theta^2 = 0 \rightarrow \Theta \approx r^{-1}$$
 ... GR-like behavior

•
$$\Theta_x + \Theta^2 \neq 0 \rightarrow \text{e.g. constraint on } g_{uu}$$

Results: *rp*-component

The EGB field equations *rp***-component** takes the form:

$$\begin{split} (D-3)\Theta_{,p} - 2\gamma\kappa \Big[(D-5)(2g^{mn}\Theta_{,m}{}^sR_{pn} - {}^sR\Theta_{,p}) \\ - 2(D-3)(D-4)\Theta_{,u}\Theta_{,p} - (D-3)^2(D-4)\Theta^2\Theta_{,p}g_{uu} \\ - (D-3)(D-4)\Theta\Theta_{,p}g_{uu,r} - (D-4)^2\Theta\Theta_{,p}g^{mn}g_{mn,u} \\ + (D-4)^2\Theta\Theta_{,m}g^{mn}g_{np,u} - 2(D-3)(D-4)\Theta_{,p}\Theta_{,r}g_{uu} \\ + (\Theta_{,r} + \Theta^2)(D-4)\big(2(D-3)\Theta_{,p}g_{uu} \\ + (D-3)\Theta g_{uu,p} - 2g^{mn}g_{m[p,u||n]}\big) \Big] = 0 \end{split}$$

For *simplicity* and in *analogy with GR* (coordinate freedom) we set:

$$\Theta_{,p} = 0$$
 that is $\Theta = \Theta(r, u)$

Results: *rp*-component

and then the *rp*-component simplifies to:

$$2\gamma\kappa(D-4)(\Theta_{,r}+\Theta^{2})\big((D-3)\Theta g_{uu,p}-2g^{mn}g_{m[p,u||n]}\big)=0$$

- identically satisfied for $\Theta_{,r} + \Theta^2 = 0$
- combination with the rr-component

$${}^{s}\mathcal{R}_{||p} = e^{2\int \Theta dr}\Theta(D-3)h^{kl}\Big[(D-3)h_{kl,u||p} - (D-2)h_{kp,u||l}\Big]$$

where ${}^s\mathcal{R}$ is the transverse space scalar curvature and ${}_{||p}$ its compatible covariant derivative

rr-component
rp-component
ru-component, etc.
Constraints on the Weyl tensor

Results: ru-component

Using the above assumptions, *ru*-component takes the form:

$$\begin{split} &\frac{1}{2}{}^{s}R-\Lambda+(D-2)\Big(\Theta_{,u}+\frac{1}{2}g^{kl}g_{kl,u}+\frac{1}{2}\Theta g_{uu,r}+\Theta_{r}g_{uu}+\frac{1}{2}(D-1)\Theta^{2}g_{uu}\Big)\\ &+2\gamma\kappa\Big[(D-4){}^{s}R\Theta_{,u}+(D-2)(D-3)(D-4)\Theta^{2}\Theta_{,u}g_{uu}\\ &+\frac{1}{2}(D-4)\Theta\big({}^{s}Rg^{kl}-2{}^{s}R^{kl}\big)g_{kl,u}+\frac{1}{2}(D-4)\Theta^{s}Rg_{uu,r}\\ &+(D-3)(D-4)\Theta\Theta_{,u}g^{kl}g_{kl,u}+(D-3)(D-4)\Theta\Theta_{,r}g_{uu}g^{kl}g_{kl,u}\\ &+\frac{1}{2}(D-2)(D-3)(D-4)\Theta^{3}g_{uu}g_{uur}-\frac{1}{4}(D-3)(D-4)\Theta^{2}g^{ij}g^{kl}g_{ik,u}g_{jl,u}\\ &+\frac{1}{4}\big({}^{s}R_{ikjl}^{2}-4{}^{s}R_{kl}^{2}+{}^{s}R^{2}\big)+\frac{1}{2}(D-4){}^{s}Rg_{uu}(2\Theta_{,r}+(D-3)\Theta^{2})\\ &+\frac{1}{4}(D-2)(D-3)(D-4)\Theta^{2}g_{uu}^{2}\big((D-1)\Theta^{2}+4\Theta_{,r}\big)\Big]=0 \end{split}$$

Combination with the previous equations.

Results also for pq, up, and uu components, however, even more messy.

Results: Additional constraints – Weyl type

The **Weyl** tensor frame **irreducible components** are:

$$\begin{split} & \Psi_{0^{ij}} = 0 \\ & \Psi_{1T^i} = 0 \\ & \Psi_{2S} = \frac{D-3}{D-1} P \\ & \Psi_{2^{ij}} = 0 \\ & \Psi_{2^{ij}} = 0 \\ & \Psi_{3T^i} = m_i^p \frac{D-3}{D-2} V_p \\ & \Psi_{3^{ij}} = m_i^p m_j^q \frac{1}{D-2} \left({}^S R_{pq} - \frac{g_{pq}}{D-2} {}^S R \right) \\ & \Psi_{3^{ijk}} = m_i^m m_j^p m_k^n m_l^q {}^S C_{mpnq} \\ & \Psi_{3^{ijk}} = m_i^p m_j^m m_k^q \left(X_{pmq} - \frac{2}{D-3} g_{p[m} X_{q]} \right) \\ & \Psi_{4^{ij}} = m_i^p m_j^q \left(W_{pq} - \frac{g_{pq}}{D-2} W \right) \end{split}$$

with

•
$$X_q \equiv g^{pm} X_{pmq}$$
 and $W \equiv g^{pq} W_{pq}$

• ${}^{S}C_{mpnq}$, ${}^{S}R_{pq}$, and ${}^{S}R$ encoding the transverse space curvature

Coefficients , P, V_p , X_{pmq} and W_{pq} are ...

Results: Additional constraints – Weyl type

Coefficients , P, V_p , X_{pmq} and W_{pq} are ...

$$\begin{split} P &= \left(\frac{1}{2}g_{uu,r} - \Theta g_{uu}\right)_{,r} + \frac{s_R}{(D-2)(D-3)} - 2\Theta_{,u} \\ V_p &= -\frac{1}{2}g_{uu,rp} - \frac{1}{D-3}g^{mn}\left(g_{m[p,u||n]}\right) + \Theta\left[g_{uu,p} - \frac{1}{2}g^{rn}g_{np,u} - \frac{1}{2(D-3)}g^{rn}g_{np,u}\right] \\ X_{pmq} &= g_{p[m,u||q]} \end{split}$$

$$\Lambda pmq - gp[m,u||q]$$

$$W_{pq} = -\frac{1}{2}g_{uu||pq} - \frac{1}{2}g_{pq,uu} + \frac{1}{4}g_{uu,r}g_{pq,u} + \frac{1}{4}g^{mn}g_{mp,u}g_{nq,u} - \frac{1}{2}\Theta g_{uu}g_{pq,u}$$

In addition to the field equations, we have to employ conditions:

$$\Psi_{2S} = 0 \qquad \tilde{\Psi}_{2T^{(ij)}} = 0 \qquad \tilde{\Psi}_{2^{ijkl}} = 0 \qquad \tilde{\Psi}_{3^{ijk}} = 0$$

We are primarily interested in such RT spacetimes, where the only non-vanishing Weyl component is:

$$\Psi_{4^{ij}}=m_i^pm_j^q\left(W_{pq}-rac{g_{pq}}{D-2}\,g^{mn}W_{mn}
ight)$$

i.e. Weyl type N in D > 4

Summary

Robinson–Trautman solutions to **Einstein–Gauss–Bonnet** gravity:

- we have derived the explicit form of the EGB field equations
- we have identified distinct subclasses
- we try to employ additional constraints on the Weyl tensor to find a generic Weyl type N solution in contrast to D > 4 GR

This is almost complete; however, it is still a work in progress.

This talk will be summarised in the upcoming paper:

Robinson—Trautman spacetimes in the Einstein-Gauss-Bonnet theory N. Astudillo Neira, R. Švarc, hopefully appear soon on arXive

Thank you for your attention!